

Diverse Image-to-Image Translation via Disentangled Representations

Code available!

<http://bit.ly/DRIT-ECCV18>



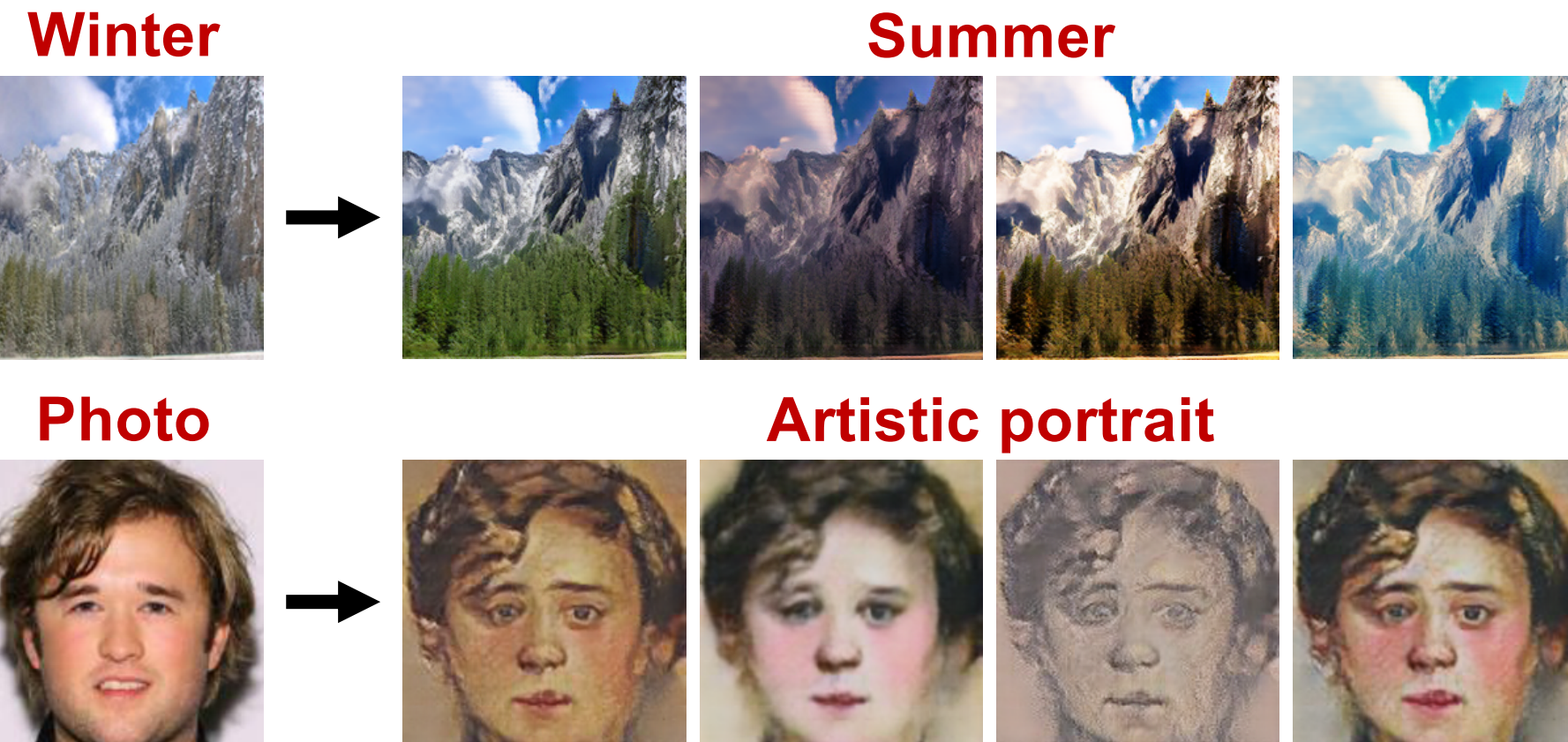
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Google Cloud

Image-to-image translation



Challenges

1. Lack of aligned training pairs
2. Multiple possible outputs given single input image

	Paired data	Unpaired data
One-to-one	Pix2pix [Isola et al.]	DiscoGAN [Kim et al.] CycleGAN [Zhu et al.] UNIT [Liu et al.]
One-to-many	BicycleGAN [Zhu et al.] Pix2pixHD [Wang et al.]	DRIT (Ours)

Contributions

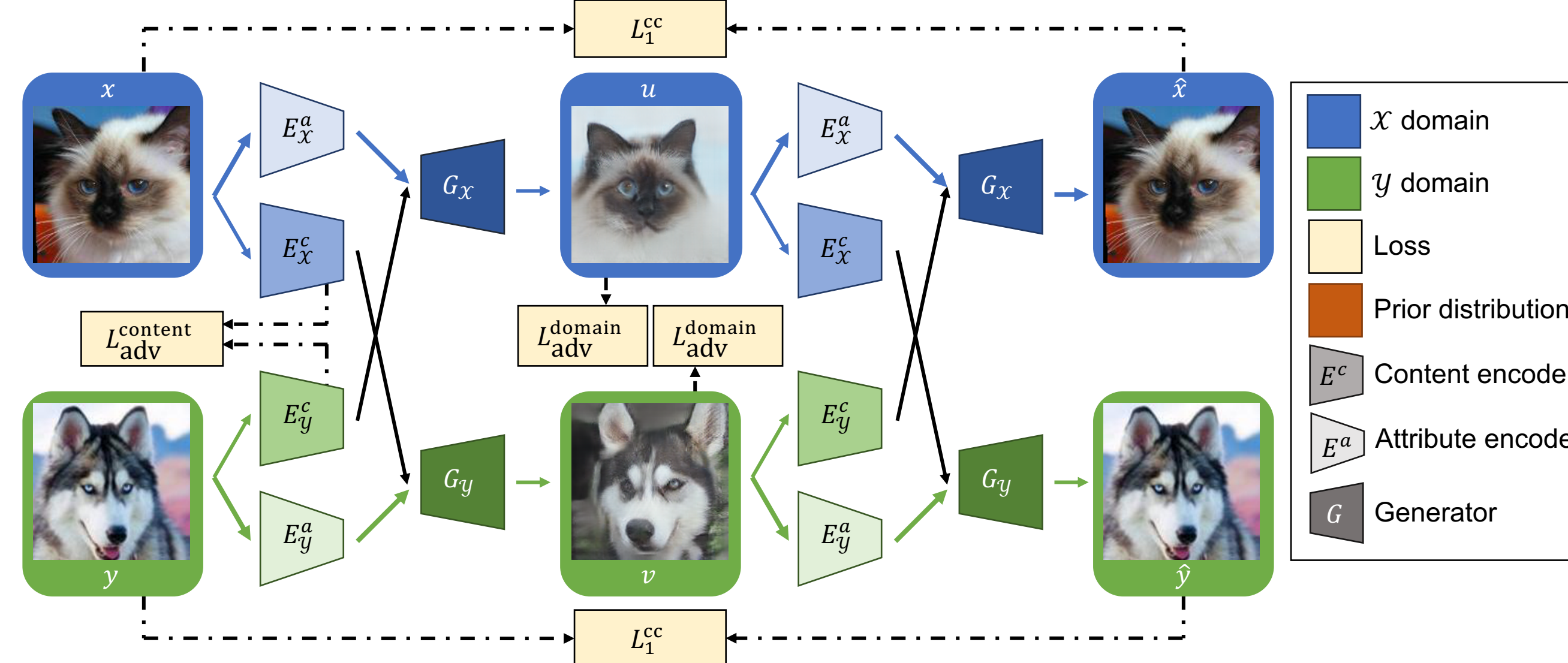
1. Disentangled representation & cross cycle consistency
2. Diverse translation from unpaired data
3. Competitive performance on domain adaptation

References

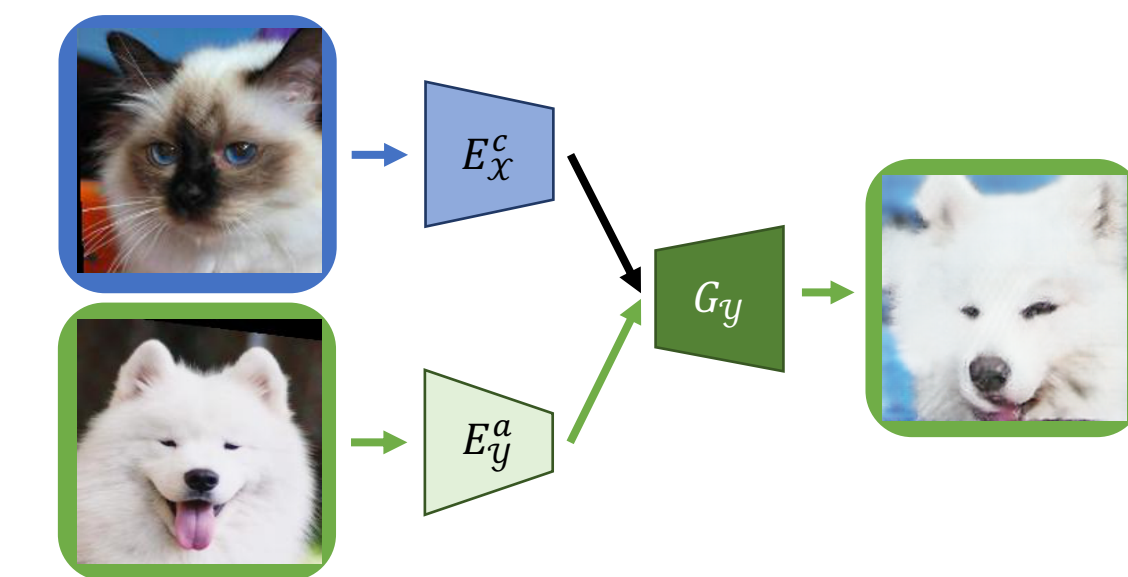
- [1] Liu et al. Unsupervised Image-to-Image Translation Networks. In *NIPS*, 2017
[2] Zhu et al. Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks. In *ICCV*, 2017
[3] Zhu et al. Toward Multimodal Image-to-Image Translation. In *NIPS*, 2017

Disentangled representation for image-to-image translation (DRIT)

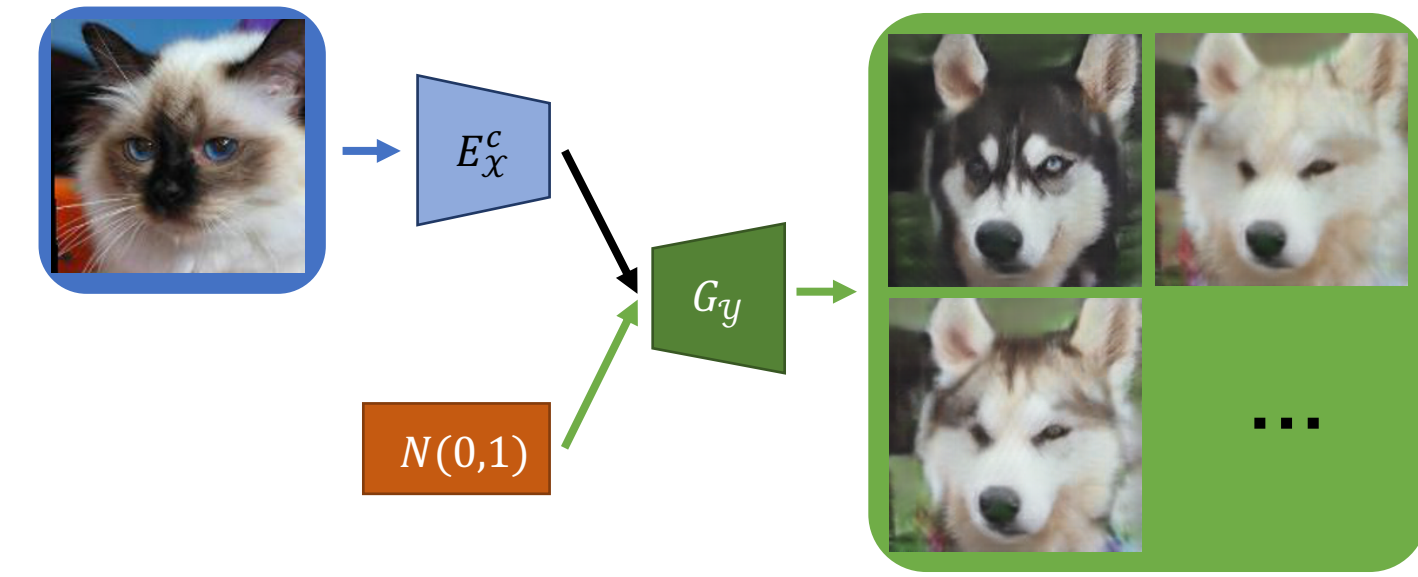
Training



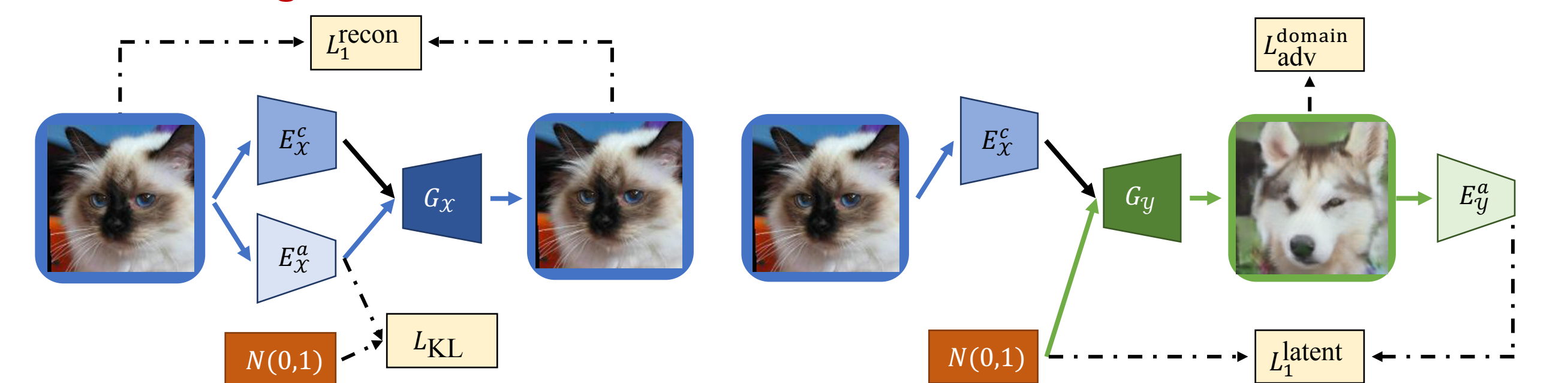
Example guided translation



Randomly sampled translation

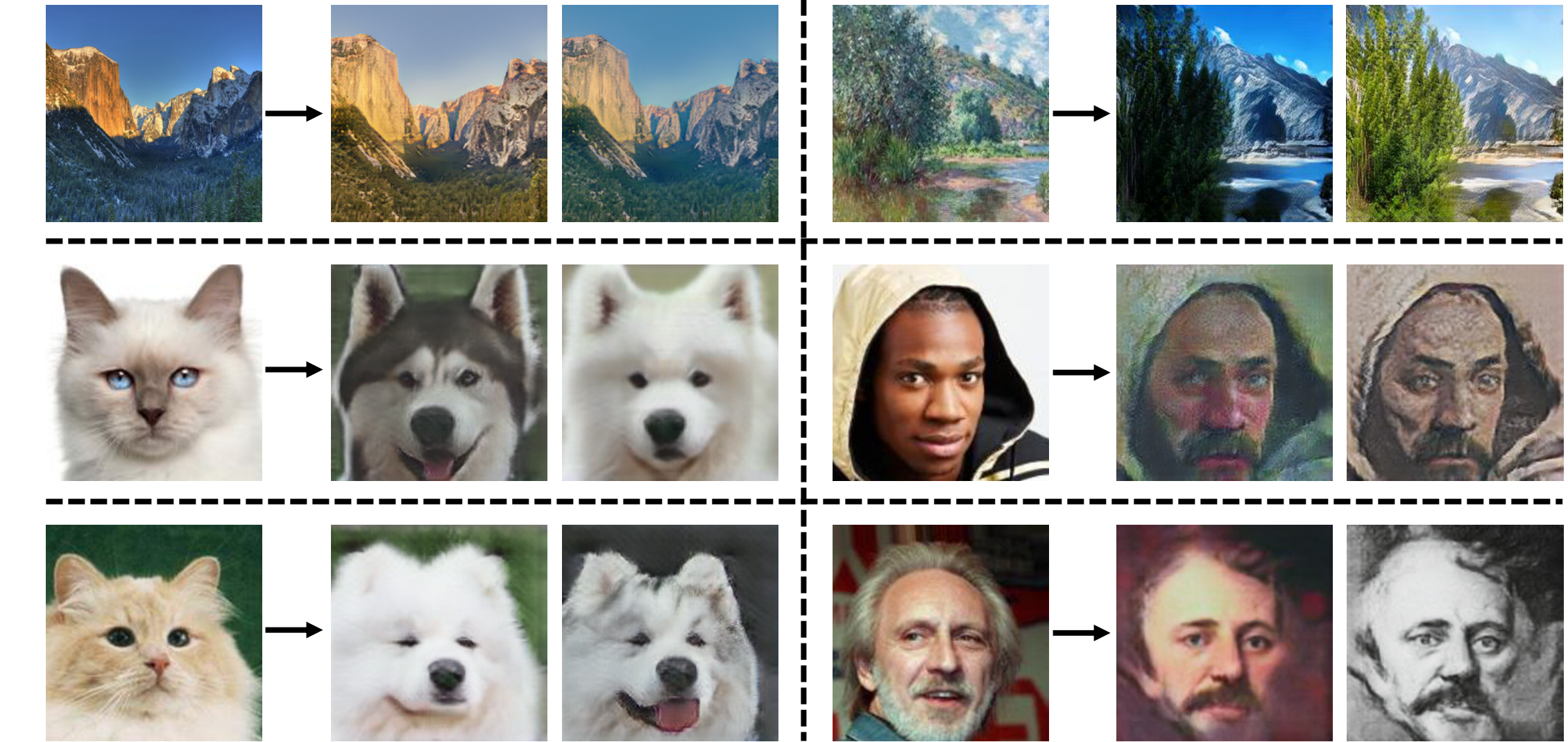


Other training loss

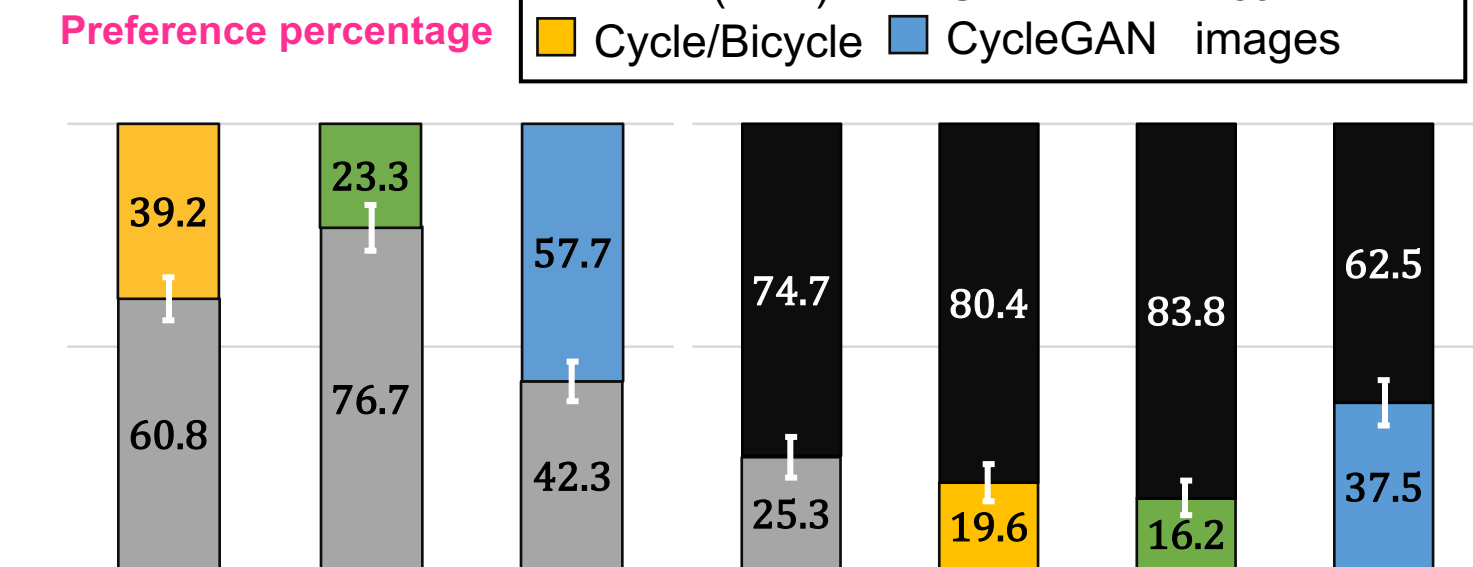


Experimental results

Visual results



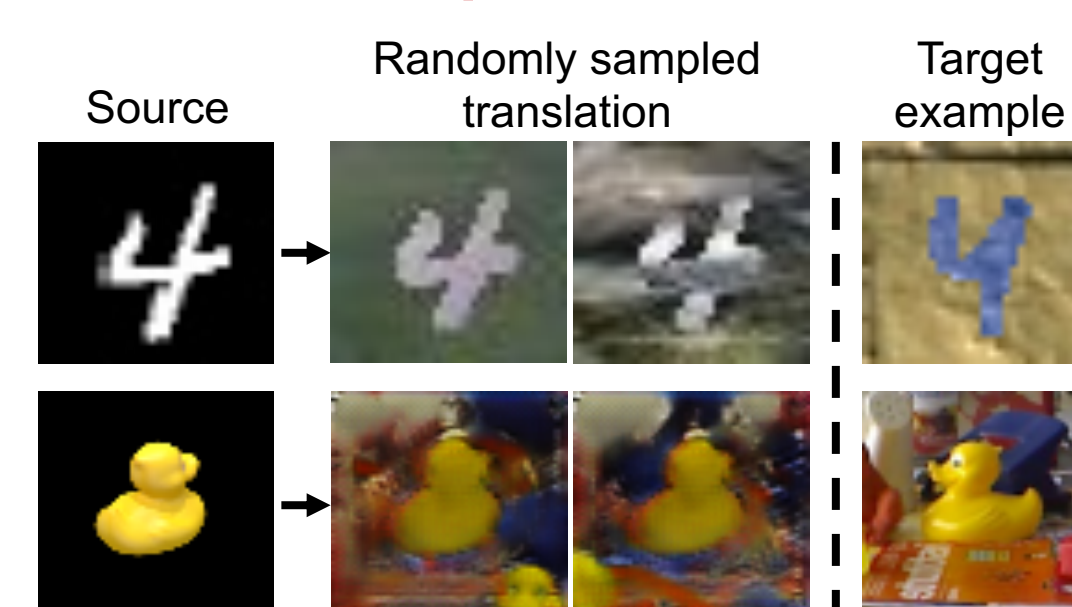
Realism:



Diversity: LPIPS score

Method	Diversity ↑
Real images	.448 ± .012
DRIT	.424 ± .010
UNIT [1]	.406 ± .022
CycleGAN [2]	.413 ± .008
Cycle/Bicycle	.399 ± .009

Domain adaptation



	(a) MNIST-M	(b) LineMOD
Model	Classification Accuracy (%)	Mean Angle Error (°)
Source-only	56.6	73.7 (89.2)
CycleGAN [2]	74.5	47.45
Ours, ×1	86.93	42.06
Ours, ×3	90.21	37.35
Ours, ×5	91.54	34.4
Target-only	96.5	12.3 (6.47)